

# Extending Calabi's duality

José Antonio Sánchez Pelegrín

Departamento de Geometría y Topología, Universidad de  
Granada

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In this conference we will show a **correspondence** between solutions of two second order nonlinear elliptic PDE as well as some geometric consequences. Namely, the **minimal** and **maximal** surface equation in the following ambiances:

- 1  $\mathbb{R}^3$  and  $\mathbb{L}^3$
- 2 Riemannian and Lorentzian warped product spaces

# Calabi's duality

Our first result is due to Calabi, who found a correspondence between local solutions to the minimal surface equation in  $\mathbb{R}^3$  and local solutions to the maximal surface equation in  $\mathbb{L}^3$ .

# Calabi's duality

## Minimal surface

A surface  $M \subset \mathbb{R}^3$  is **minimal** if its mean curvature is identically zero.

Minimal surfaces are critical points for the area functional for all compactly supported normal variations.

# Calabi's duality

## Minimal surface equation in $\mathbb{R}^3$

Given a smooth function  $u$  defined on a domain  $\Omega \subset \mathbb{R}^2$ , its graph

$$\Sigma_u = \{(p, u(p)) : p \in \mathbb{R}^2\}$$

defines a minimal surface in  $\mathbb{R}^3$  if and only if  $u$  satisfies

$$\operatorname{div} \left( \frac{Du}{\sqrt{1 + |Du|^2}} \right) = 0.$$

# Calabi's duality

## Spacelike surface

An immersed surface  $M$  in the Lorentz-Minkowski spacetime  $\mathbb{L}^3$  is called **spacelike** if the induced metric on  $M$  is Riemannian.

# Calabi's duality

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## Maximal surface

A spacelike surface  $M \subset \mathbb{L}^3$  is **maximal** if its mean curvature is identically zero.

# Calabi's duality

## Maximal surface equation in $\mathbb{L}^3$

Given a smooth function  $\omega$  defined on a domain  $\Omega \subset \mathbb{R}^2$ , its graph

$$\Sigma_\omega = \{(p, \omega(p)) : p \in \mathbb{R}^2\}$$

defines a maximal surface in  $\mathbb{L}^3$  if and only if  $\omega$  satisfies


$$\operatorname{div} \left( \frac{D\omega}{\sqrt{1 - |D\omega|^2}} \right) = 0,$$
$$|Du|^2 < 1.$$



# Calabi's duality

In 1970, Calabi<sup>1</sup> proved that there exists a one-to-one correspondence between solutions to the minimal surface equation in  $\mathbb{R}^3$  and solutions to the maximal surface equation in  $\mathbb{L}^3$ .

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<sup>1</sup>E. Calabi, Examples of Bernstein problems for some nonlinear equations, *P. Symp. Pure Math.*, **15** (1970), 223–230. 

# Calabi's duality

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In particular, given a minimal graph  $\Sigma_u$  over a simply connected domain  $\Omega \subseteq \mathbb{R}^2$ , we can find a maximal graph  $\Sigma_\omega$  over  $\Omega$  and vice versa

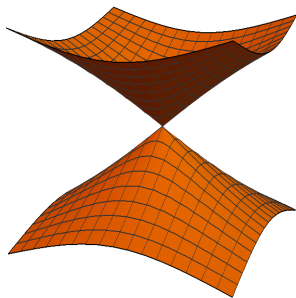
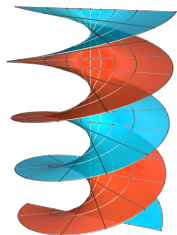
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# Calabi's duality

## Examples of dual graphs

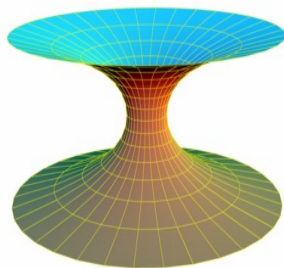
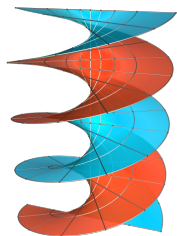
This duality converts the helicoid in  $\mathbb{R}^3$ ,  $u = \arctan\left(\frac{y}{x}\right)$  to the Lorentzian catenoid  $\omega = \sinh^{-1}\left(\sqrt{x^2 + y^2}\right)$ .



# Calabi's duality

## Examples of dual graphs

Conversely, the helicoid in  $\mathbb{L}^3$ ,  $\omega = \arctan\left(\frac{y}{x}\right)$  recovers the Euclidean catenoid  $u = \cosh^{-1}\left(\sqrt{x^2 + y^2}\right)$ .



# Calabi's duality

## Bernstein Theorem <sup>2</sup>

The only entire solutions to the minimal surface equation in  $\mathbb{R}^3$  are the affine functions.

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<sup>2</sup>S. Bernstein, Sur un théorème de géométrie et son application aux équations aux dérivées partielles du type elliptique, *Comm. de la Soc. Math. de Kharkow*, **15** (1915), 38–45.

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# Calabi's duality

## Bernstein Theorem <sup>2</sup>


The only entire solutions to the minimal surface equation in  $\mathbb{R}^3$  are the affine functions.

## Calabi-Bernstein Theorem <sup>1</sup>

The only entire solutions to the maximal surface equation in  $\mathbb{L}^3$  are the affine functions satisfying  $|Du| < 1$ .

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<sup>2</sup>S. Bernstein, Sur un théorème de géométrie et son application aux équations aux dérivées partielles du type elliptique, *Comm. de la Soc. Math. de Kharkow*, **15** (1915), 38–45.

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# Calabi's duality

This correspondence was also obtained using the local **Enneper-Weierstrass representation** of a minimal surface in  $\mathbb{R}^3$  and the local Enneper-Weierstrass representation of a maximal surface in  $\mathbb{L}^3$ , reproving with a very different approach the equivalence between Bernstein and Calabi-Bernstein theorems <sup>3</sup>.

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<sup>3</sup>F.J.M. Estudillo and A. Romero, Generalized maximal surfaces in Lorentz-Minkowski space  $\mathbb{L}^3$ , *Math. Proc. Cambridge*, **111** (1992), 515–524.

# Calabi's duality

Later, this duality was extended to **product spaces**<sup>4</sup>. Hence, it was found a local correspondence between solutions of the minimal surface equation in a 3-dimensional Riemannian product space  $M^2 \times \mathbb{R}$  and solutions of the maximal surface equation in a 3-dimensional Lorentzian product space  $M^2 \times (-\mathbb{R})$ .

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<sup>4</sup>A.L. Albuje and L.J. Alías, Calabi-Bernstein results for maximal surfaces in Lorentzian product spaces, *J. Geom. Phys.*, **59** (2009), 620–631.



# Calabi's duality

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This correspondence was used to obtain non-trivial examples of entire maximal graphs in the Lorentzian product space  $\mathbb{H}^2 \times (-\mathbb{R})$ .

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<sup>4</sup>A.L. Albuje and L.J. Alías, Calabi-Bernstein results for maximal surfaces in Lorentzian product spaces, *J. Geom. Phys.*, **59** (2009), 620–631.

# Duality in warped product spaces

Recently, we have been able to extend this duality to a wider class of ambient manifolds. Namely, we have found a correspondence between local solutions of the minimal surface equation in a 3-dimensional **Riemannian warped product space** and local solutions of the maximal surface equation in a related 3-dimensional **standard static spacetime**.

# Duality in warped product spaces

## Riemannian warped product space

The **Riemannian warped product**  $B \times_{\frac{1}{\sqrt{\gamma}}} \mathbb{R}$  will denote the product manifold  $B \times \mathbb{R}$ , being  $(B, g_B)$  a connected Riemannian surface, endowed with the Riemannian metric

$$\bar{g} = \pi_B^*(g_B) + \frac{1}{\gamma(\pi_B)} \pi_{\mathbb{R}}^*(dt^2),$$

where  $\pi_B$  and  $\pi_{\mathbb{R}}$  denote, respectively, the projections on  $B$  and  $\mathbb{R}$  and  $\gamma$  is a smooth positive function on  $B$ .

# Duality in warped product spaces

## Minimal surface equation in $B \times \sqrt{\frac{1}{\gamma}} \mathbb{R}$

The graph of a smooth function  $u$  defined on a domain  $\Omega \subset B$ ,

$$\Sigma_u = \{(p, u(p)) : p \in B\}$$

defines a **minimal surface** in  $B \times \sqrt{\frac{1}{\gamma}} \mathbb{R}$  if and only if  $u$  satisfies

$$\operatorname{div} \left( \frac{Du}{\sqrt{\gamma + |Du|^2}} \right) = \frac{1}{2\gamma} \frac{g_B(D\gamma, Du)}{\sqrt{\gamma + |Du|^2}}. \quad (\text{R})$$

# Duality in warped product spaces

## Standard static spacetimes

A 3-dimensional **standard static spacetime**  $B \times_{\sqrt{\gamma}} (-\mathbb{R})$  is defined as the product manifold  $B \times \mathbb{R}$ , being  $(B, g_B)$  a connected Riemannian surface, endowed with the Lorentzian metric

$$\bar{g} = \pi_B^*(g_B) - \gamma(\pi_B)\pi_{\mathbb{R}}^*(dt^2),$$

where  $\pi_B$  and  $\pi_{\mathbb{R}}$  denote, respectively, the projections on  $B$  and  $\mathbb{R}$  and  $\gamma$  is a smooth positive function on  $B$ .

# Duality in warped product spaces

## Physical relevance of standard static spacetimes

In these spacetimes there exists an **irrotational timelike Killing** vector field that defines a family of observers that measure a spatial universe that does not change with time.

Standard static spacetimes include some relevant models such as Einstein static universe and (exterior) Schwarzschild spacetime.

# Duality in warped product spaces

## Maximal surface equation in $B \times_{\sqrt{\gamma}} (-\mathbb{R})$

Given a smooth function  $\omega$  defined on a domain  $\Omega \subset B$ ,

$$\Sigma_\omega = \{(p, \omega(p)) : p \in B\}$$

defines a **maximal surface** in  $B \times_{\sqrt{\gamma}} (-\mathbb{R})$  if and only if  $\omega$  satisfies

$$\operatorname{div} \left( \frac{D\omega}{\sqrt{\frac{1}{\gamma} - |D\omega|^2}} \right) = \frac{\gamma g_B \left( D \left( \frac{1}{\gamma} \right), D\omega \right)}{\sqrt{\frac{1}{\gamma} - |D\omega|^2}}, \quad (\text{L.1})$$

$$|D\omega|^2 < \frac{1}{\gamma}. \quad (\text{L.2})$$

# Duality in warped product spaces

## Theorem <sup>5</sup>

Let  $\Omega \subset B$  be a simply connected domain. Then, there exists a non-trivial (i.e., non-constant) solution of the minimal surface equation in  $B \times_{\frac{1}{\sqrt{\gamma}}} \mathbb{R}$  on  $\Omega$  if and only if there exists a non-trivial solution of the maximal surface equation in  $B \times_{\sqrt{\gamma}} (-\mathbb{R})$  on  $\Omega$ .

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<sup>5</sup>J.A.S. Pelegrín, A. Romero and R.M. Rubio, An extension of Calabi's correspondence between the solutions of two Bernstein problems to more general elliptic nonlinear equations, *Math. Notes*, **5** (2018), to appear.



# Duality in warped product spaces

## Sketch of the proof

1. If we consider on  $B$  the conformal metric

$$\tilde{g} = \frac{1}{\sqrt{\gamma}} g_B,$$

we can rewrite (R) as follows

$$\widetilde{\operatorname{div}} \left( \frac{Du}{\sqrt{\gamma + |Du|^2}} \right) = 0. \quad (\tilde{R})$$

# Duality in warped product spaces

## Sketch of the proof

2. Analogously, with the conformal change of metric

$$\widehat{g} = \sqrt{\gamma} g_B,$$

we can write (L) as

$$\widehat{\operatorname{div}} \left( \frac{D\omega}{\sqrt{\frac{1}{\gamma} - |D\omega|^2}} \right) = 0, \quad (\widehat{L}.1)$$

$$|D\omega|^2 < \frac{1}{\gamma}. \quad (\widehat{L}.2)$$

# Duality in warped product spaces

## Sketch of the proof

3. If we assume now the existence of a non-trivial solution  $u$  of  $(\tilde{R})$  on  $\Omega \subset B$ , we have

$$d * (U^{\tilde{b}}) = 0,$$

where  $U := \frac{Du}{\sqrt{\gamma + |Du|^2}}$ .

# Duality in warped product spaces

## Sketch of the proof

3. If we assume now the existence of a non-trivial solution  $u$  of  $(\tilde{R})$  on  $\Omega \subset B$ , we have

$$d * (U^{\tilde{b}}) = 0,$$

where  $U := \frac{Du}{\sqrt{\gamma + |Du|^2}}$ .

4. Since  $\Omega$  is simply connected, classical Poincaré's lemma ensures the existence of  $\omega \in C^\infty(B)$  such that

$$d\omega = *(U^{\tilde{b}}).$$

# Duality in warped product spaces

## Sketch of the proof

5. After several computations we obtain that  $\omega$  satisfies

$$* \left( \left( \frac{D\omega}{\sqrt{\frac{1}{\gamma} - |D\omega|^2}} \right)^{\widehat{b}} \right) = d(-u)$$

and

$$|D\omega|^2 < \frac{1}{\gamma}.$$

Hence,  $\omega$  is a non-trivial solution of  $(\widehat{L})$  on  $\Omega$ . The converse is proved in the same way.

# Duality in warped product spaces

As a consequence of this correspondence, we can obtain new Calabi-Bernstein type results from known Bernstein type results. For instance, knowing

## Theorem <sup>6</sup>

The only entire solutions of equation (R) on the 2-dimensional sphere  $\mathbb{S}^2$  endowed with a Riemannian metric are the constants.

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<sup>6</sup>A. Romero and R.M. Rubio, Bernstein-type Theorems in a Riemannian Manifold with an Irrotational Killing Vector Field, *Mediterr. J. Math.*, **13** (2016), 1285–1290.

# Duality in warped product spaces

Combining the previous result with our duality theorem in these ambiances we obtain

## Corollary <sup>5</sup>

The only entire solutions of equation (L) on the 2-dimensional sphere  $\mathbb{S}^2$  endowed with a Riemannian metric are the constants.

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Thank you  
for your attention!